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Tuneable linearity in HfO₂ based multilevel FeFETs for neuromorphic computing

M. Lederer, T. Kämpfe, T. Ali, K. Seidel

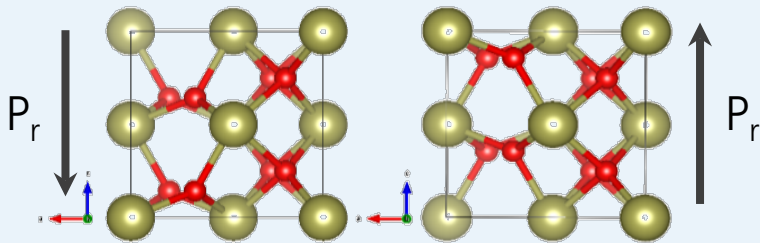


EMRS Fall 2019

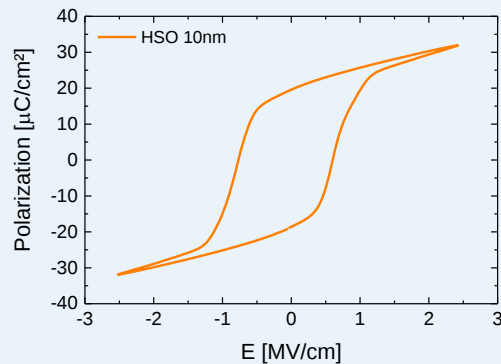
Ferroelectric Fieldeffect Transistor (FeFET)

Ferroelectricity in HfO_2

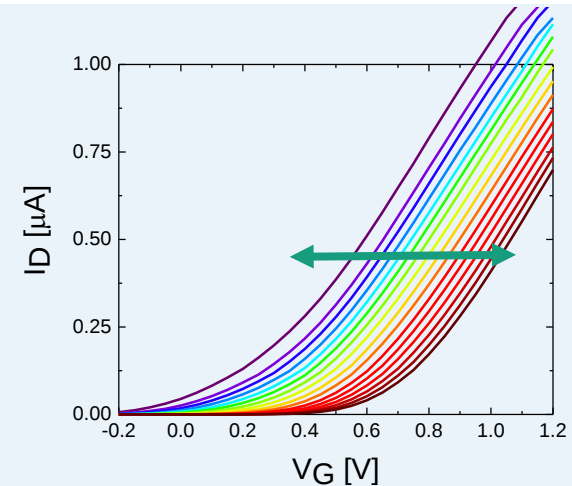
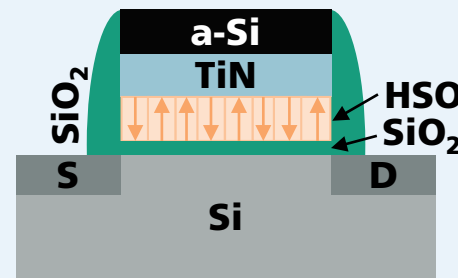
Orthorhombic (Pca2_1)



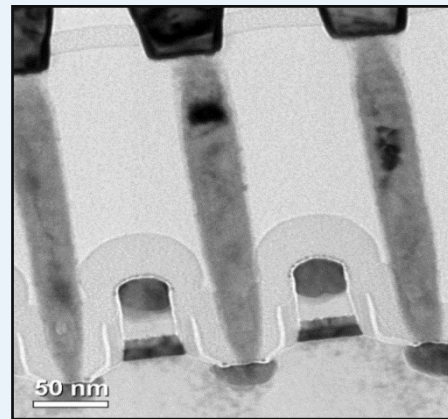
■ Stabilized by Dopants, Stress, ...



FeFET Gate Stack



28nm Proof of Concept



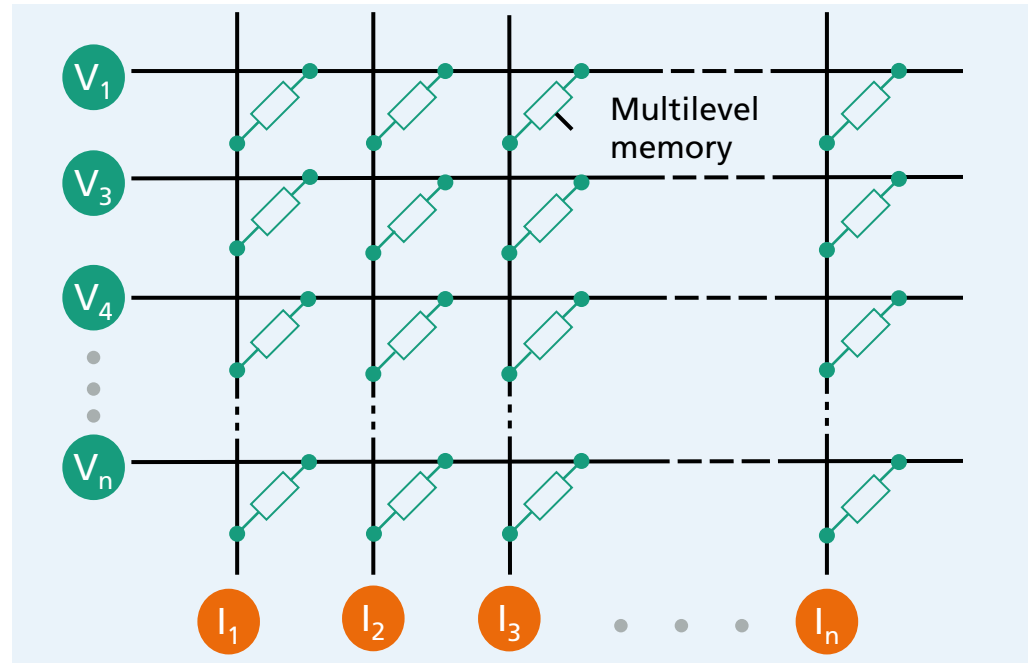
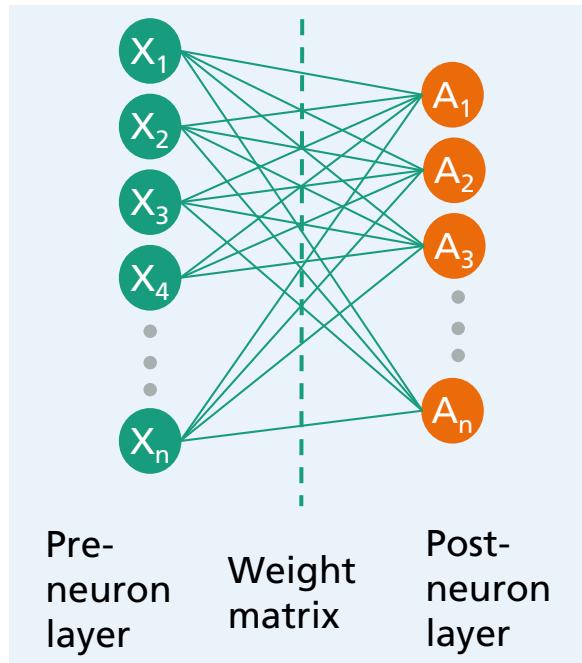
- Gate-First
- $\Delta V_T = 1-1.2 \text{ V}$
- $\pm 5 \text{ V}, < 100 \text{ ns}$
- 10^4 endurance
- 10y retention

J. Müller et al., VLSI (2012)

Neuromorphic Computing

Dot-product engine

- Conductance of crossbar array represent weight matrix
- Level-based representation
- Most efficient for fully connected layers

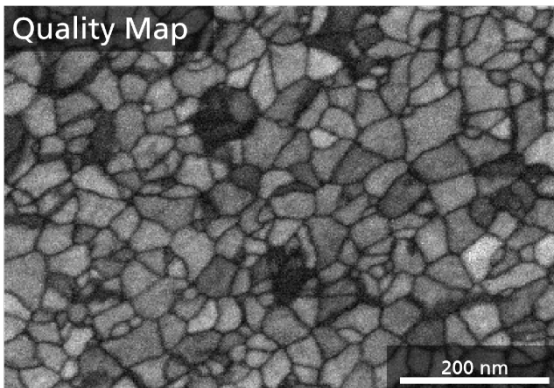


Non-Linearity Coefficient

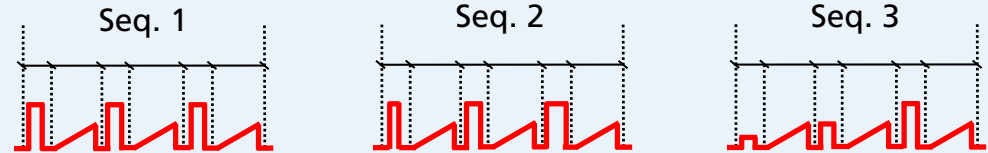
- Switching polarization of grains/domains
 - Shifting the threshold voltage

Transmission EBSD:

Quality Map

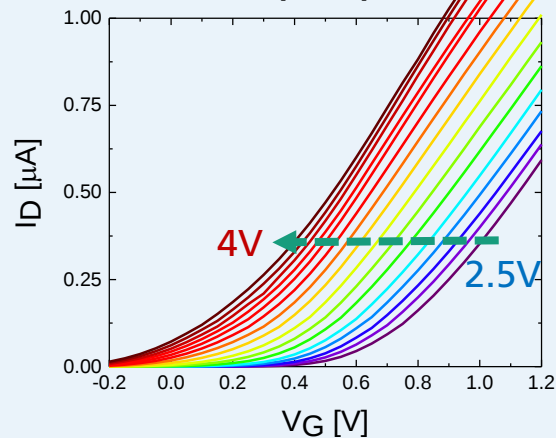


Signal Shape

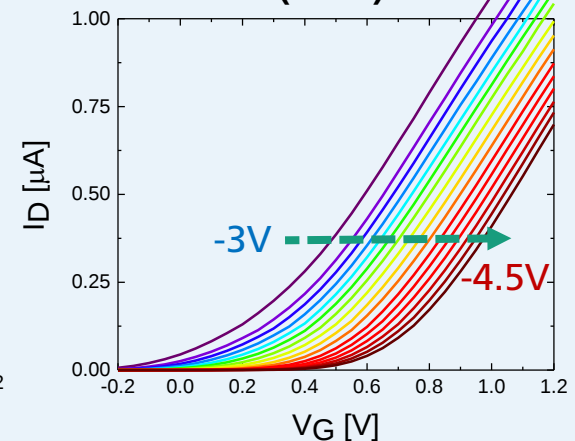


Seq. 3: 150ns W: 50 μm , L: 25 μm

Potentiation (LTP):

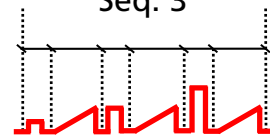


Depression (LTD):



Non-Linearity Coefficient

Seq. 3



1. Nonlinearity Fit:

$$I_{p,d} = B \left(1 - \exp \left(\frac{P - D}{A} \right) \right) + C$$

P := Pulse Number

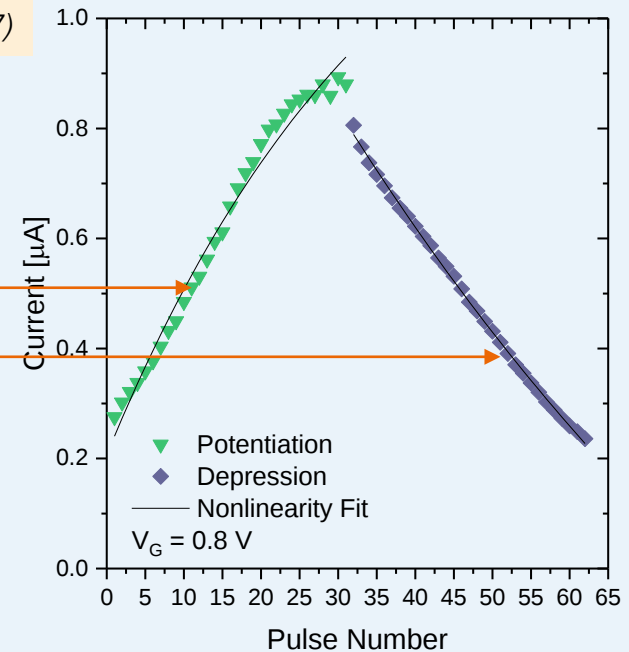
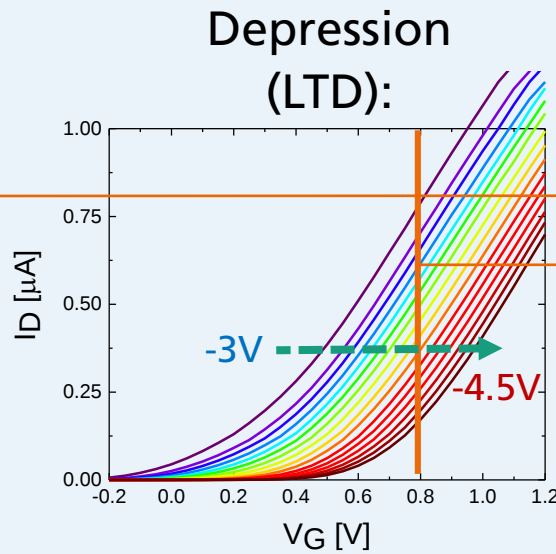
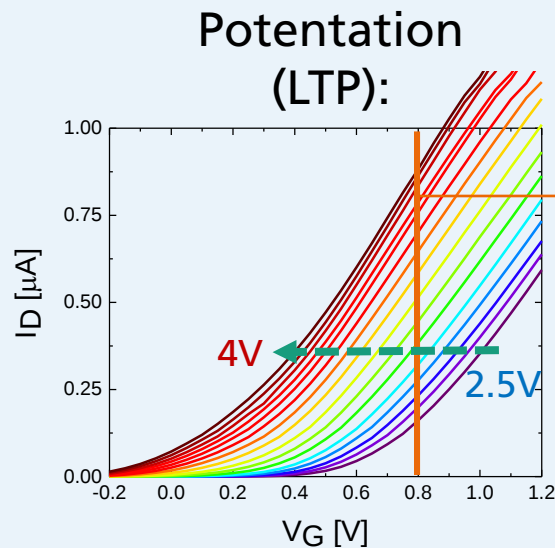
D := Start Pulse Number

2. Nonlin. Coefficient:

$$\alpha_{p,d} = \frac{1.726}{A + 0.162}$$

M. Jerry et al., IEDM (2017)

Seq. 3: 150ns W: 50 μ m, L: 25 μ m



Non-Linearity Coefficient

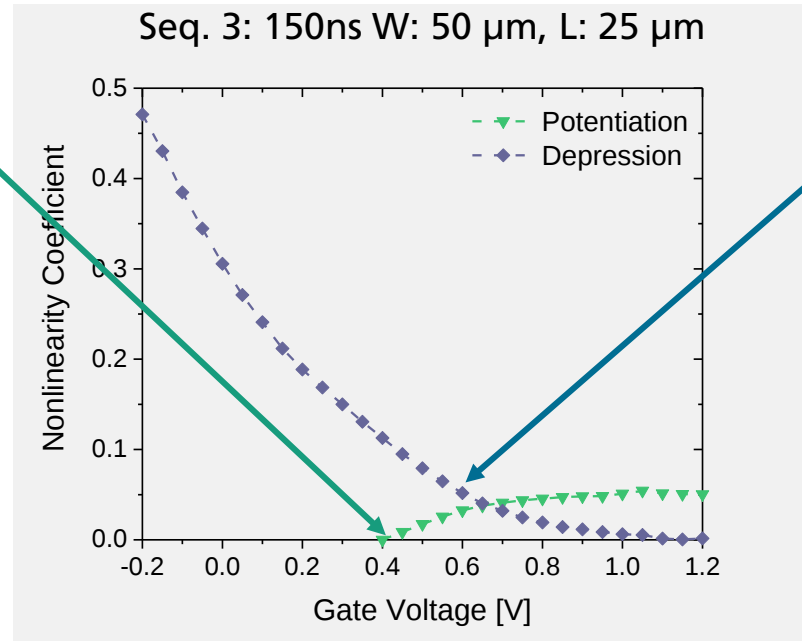
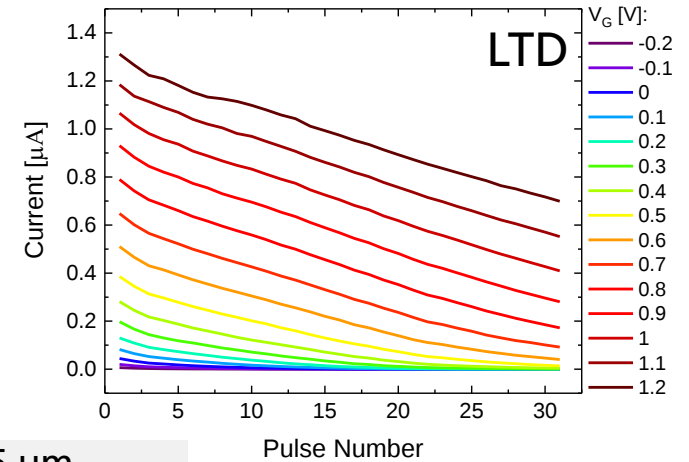
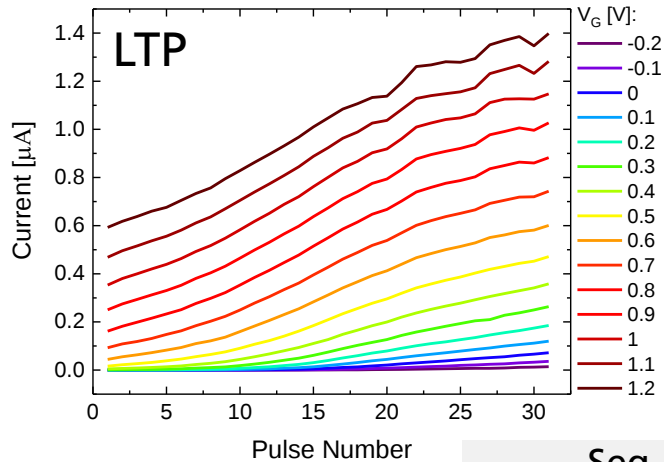
- Comparison of different non-linearities

0.21

0.12

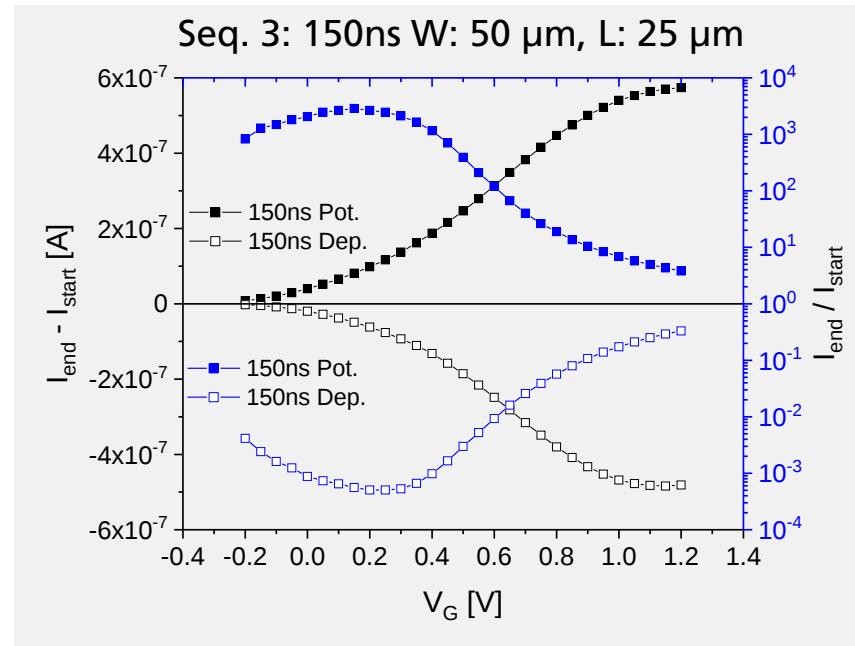
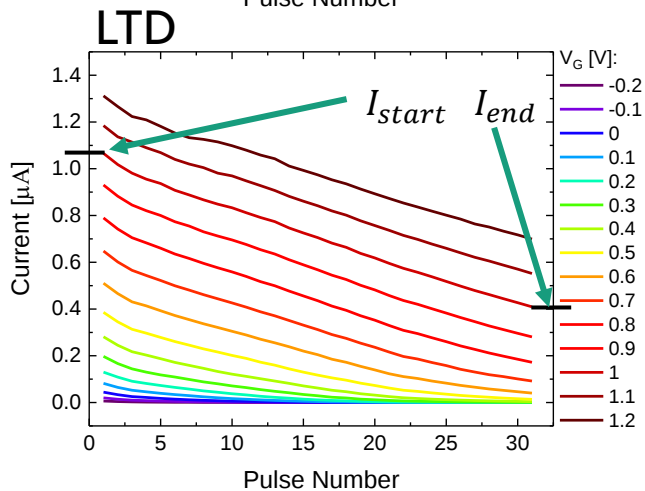
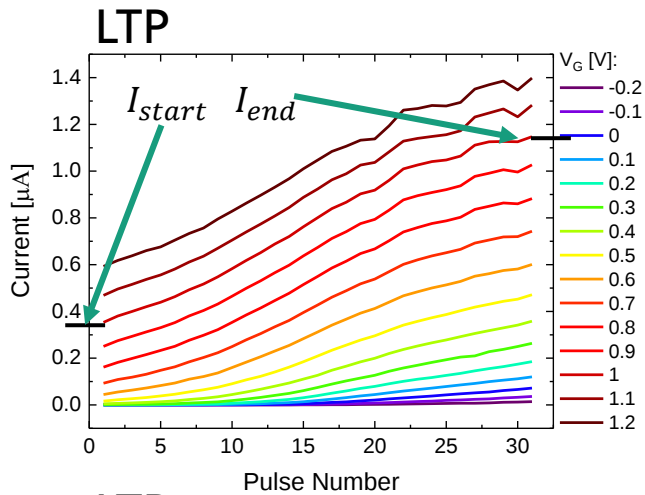
0.00 ($1.02 \cdot 10^{-7}$)

Influence of the Gate Voltage



■ Nonlinearity is strongly dependent on gate voltage

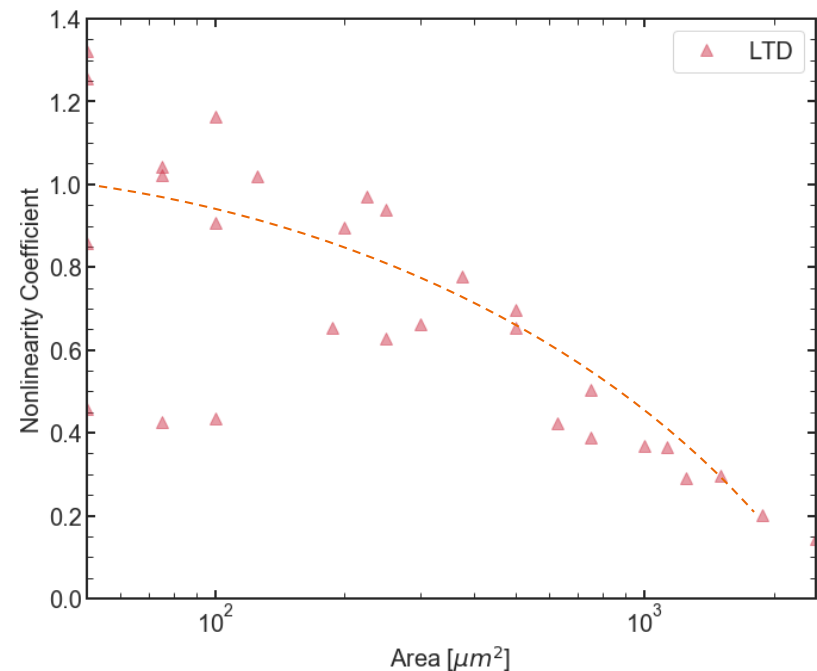
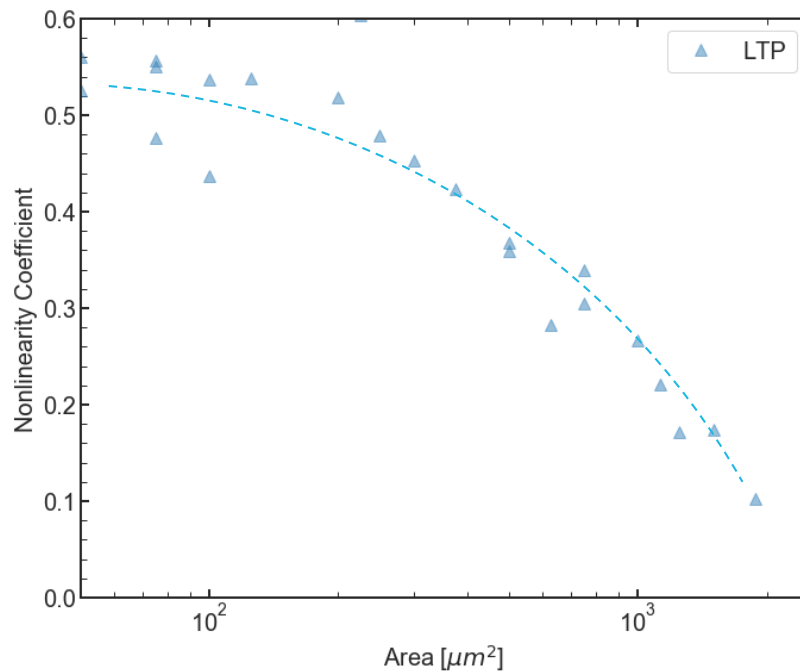
Influence of the Gate Voltage



- Dynamic range strongly dependent on gate voltage
- Relative and absolute range show maximum at different gate voltages

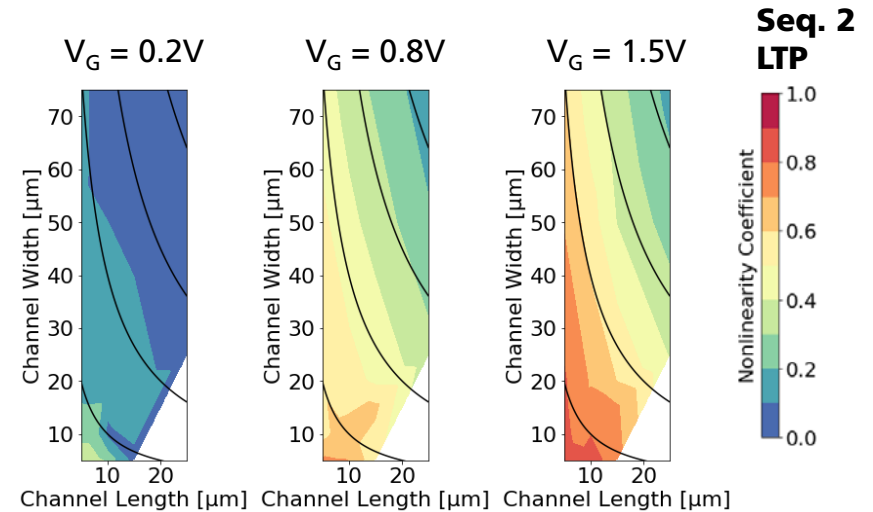
Area scaling

- Increase of nonlinearity with decreasing area
- More deviation for smaller devices? → Influence of width/length?

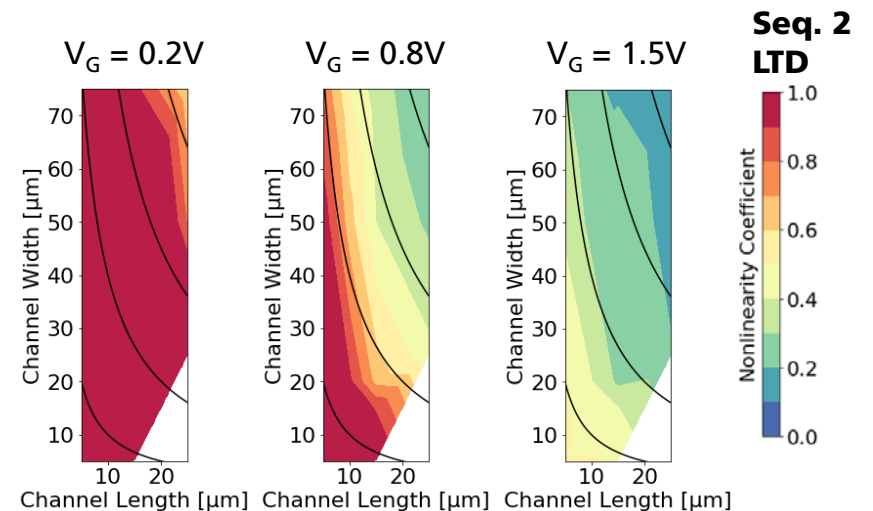


Influence of the device layout

■ Seq2 W01 Potentiation

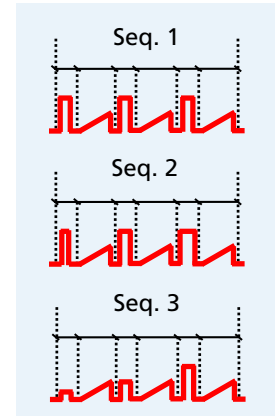
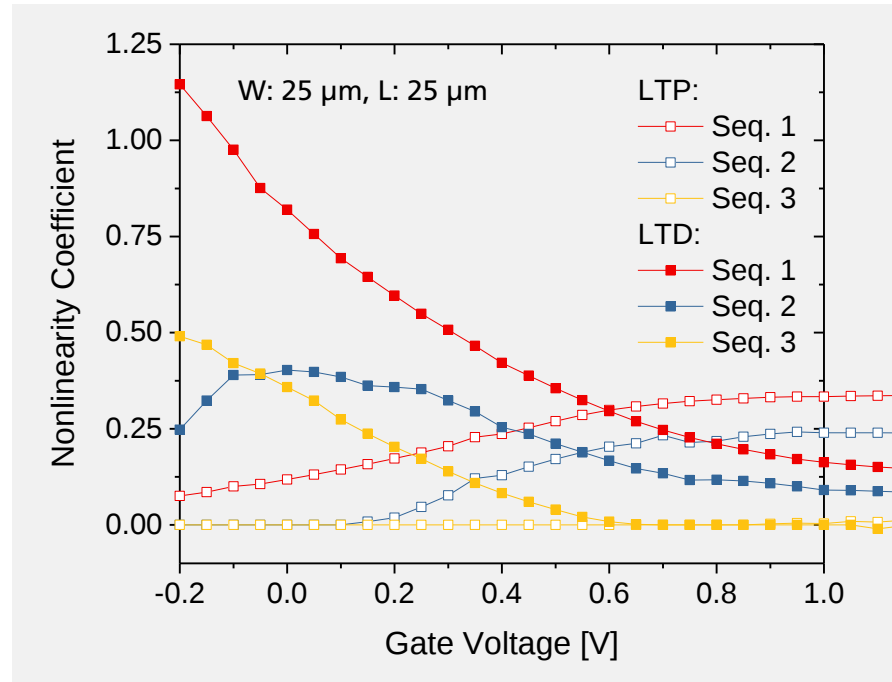
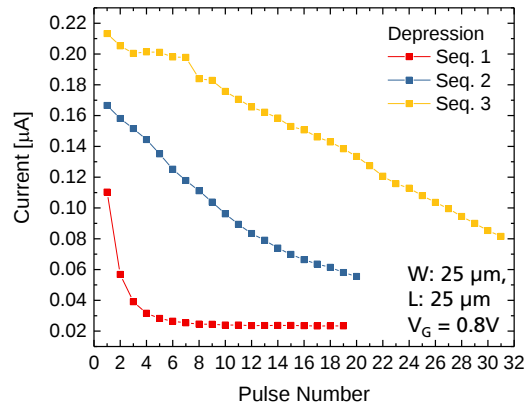


■ Seq2 W01 Depression

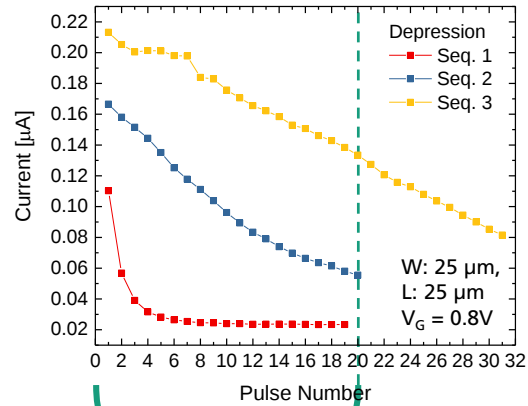


Sequence 1 – 3: Nonlinearity

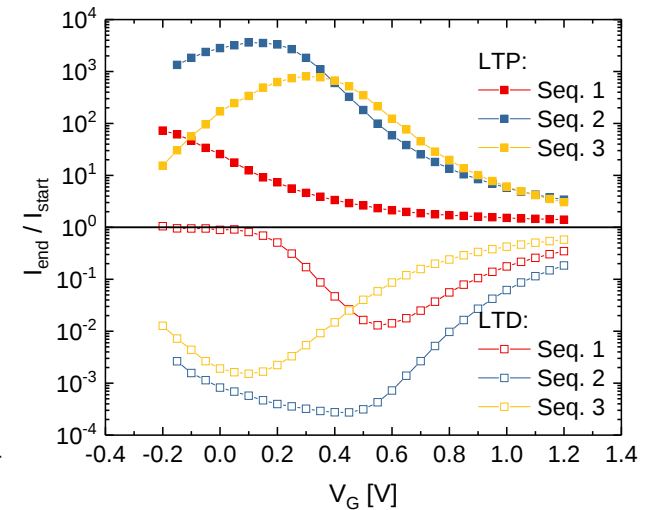
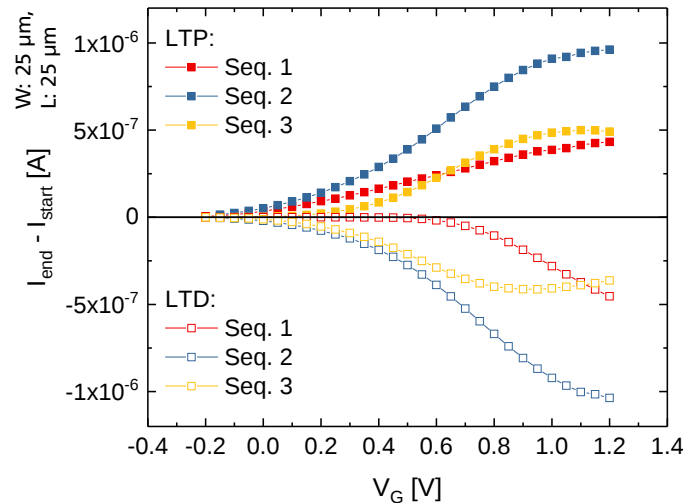
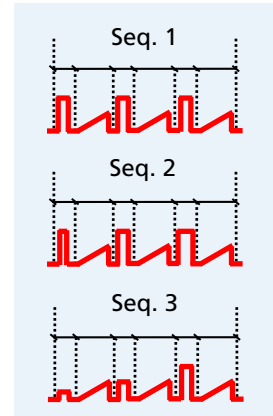
- Sequence 3 shows lowest nonlinearity



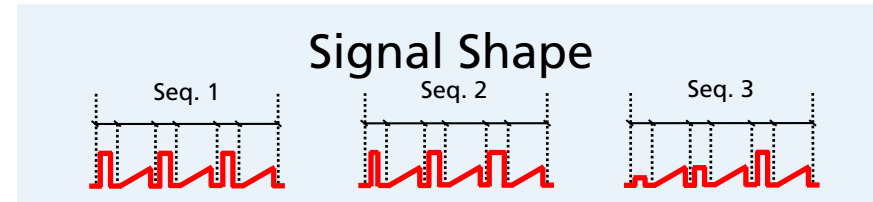
Sequence 1 – 3: Dynamic range (I_{on}/I_{off})



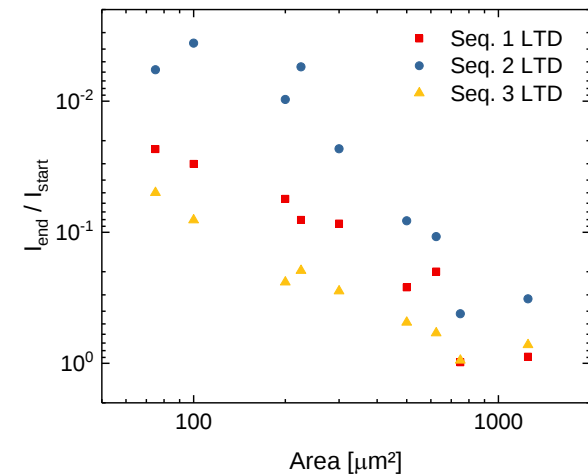
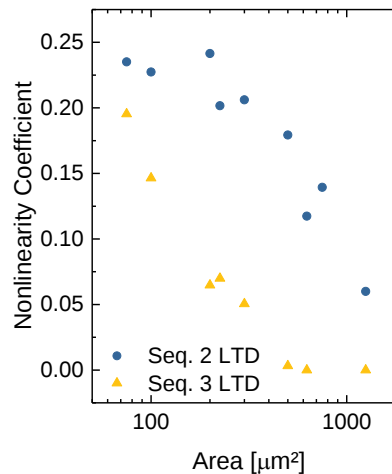
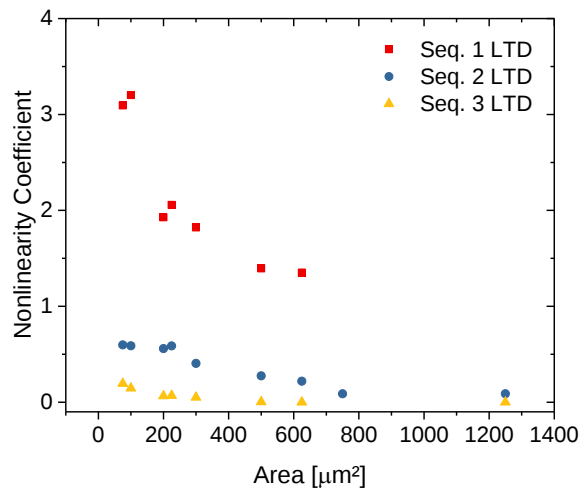
- Seq. 2 & 3 less asymmetric
- Higher variance for Seq. 2 & 3
- Dynamic range can be improved by using more pulses (Seq. 3)



Sequence 1 – 3: Area Scaling

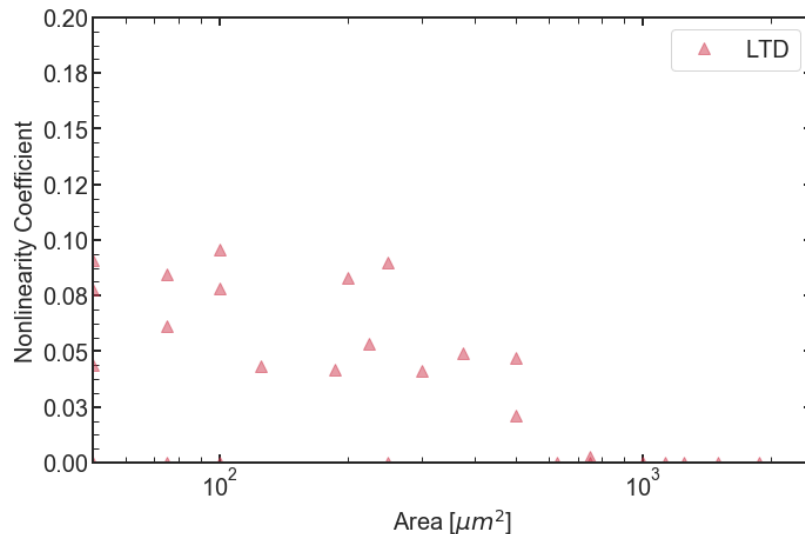
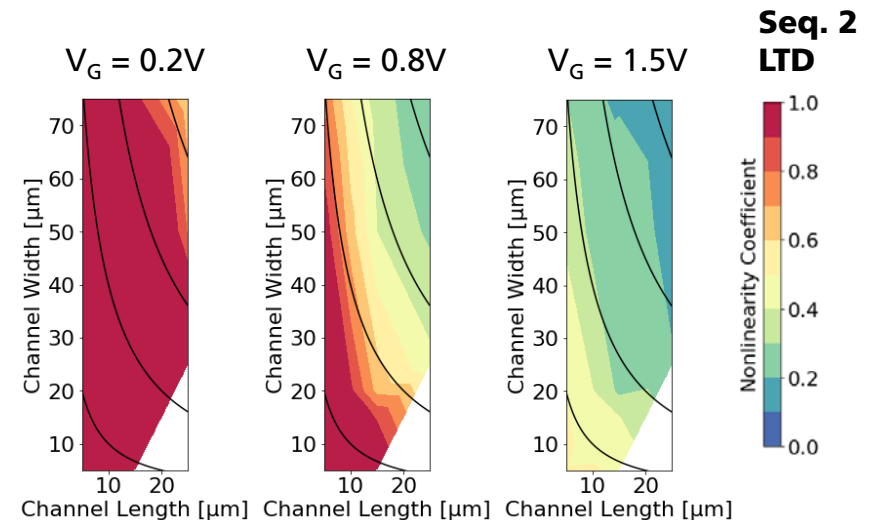
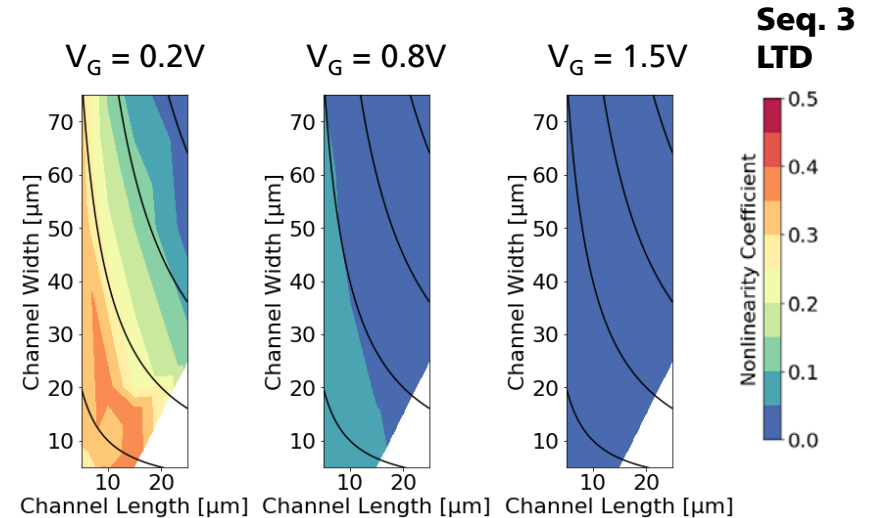


- Seq. 1 shows a very rapid increase in nonlinearity with area scaling
- Seq. 2 and 3 show slower increase, could be used for smaller devices
- Origin lies in domain structure and nucleation limited switching



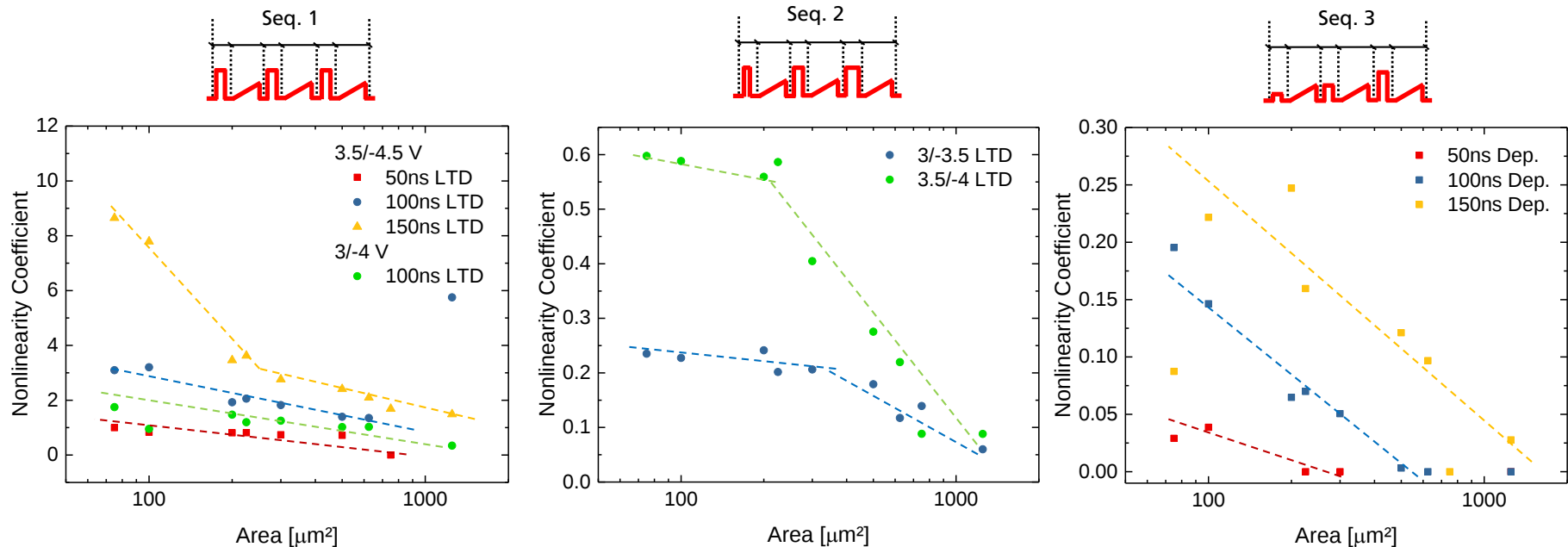
Sequence 1 – 3: Area Scaling

- Seq. 3 shows the same trend as seq. 2
- Much lower nonlinearity for seq. 3 even for the smaller devices



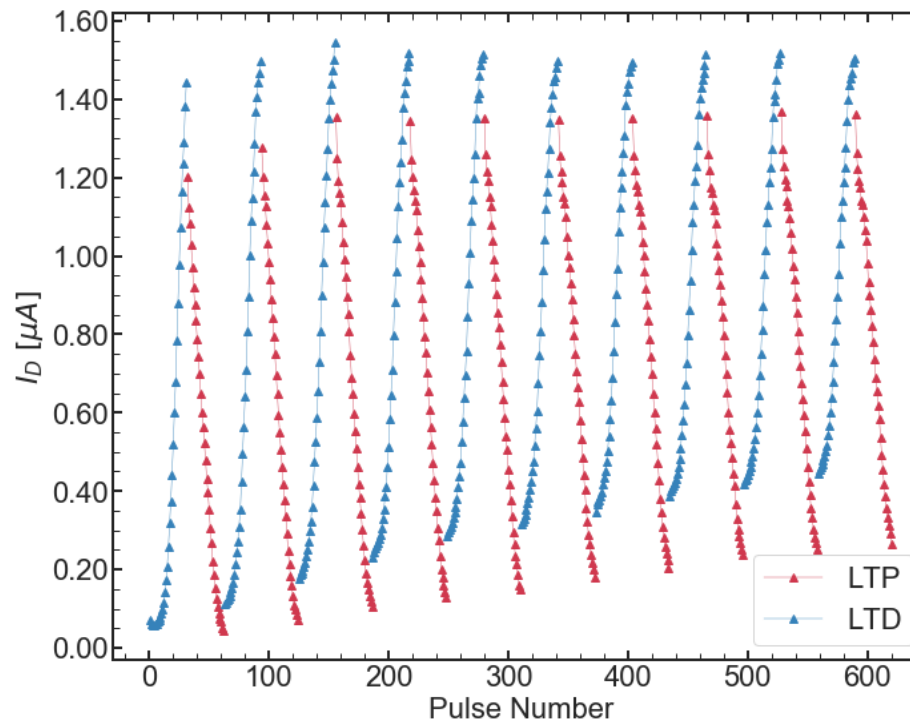
Sequence 1 – 3: Possible Adjustments for Area Scaling

- Adjusting signal shape for smaller devices improves nonlinearity



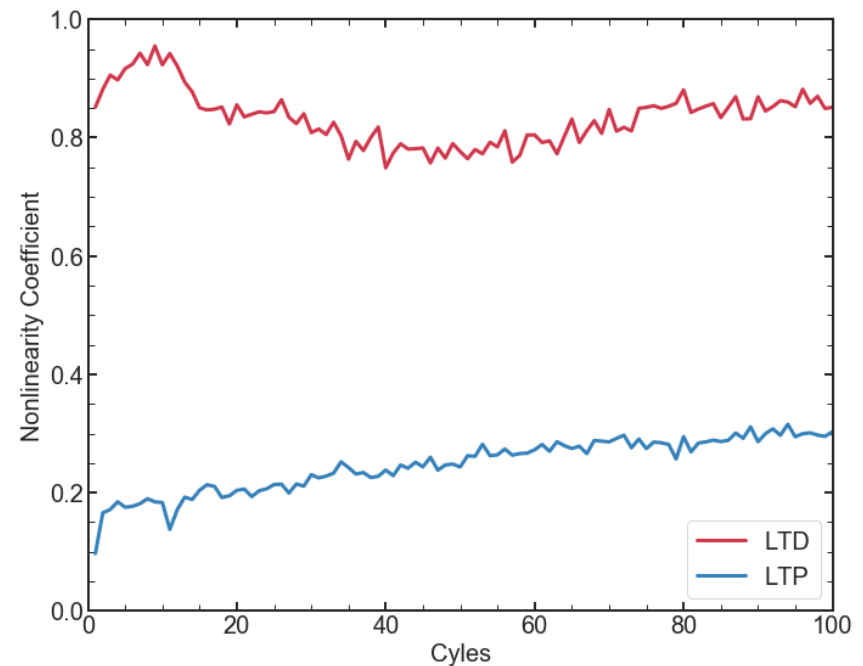
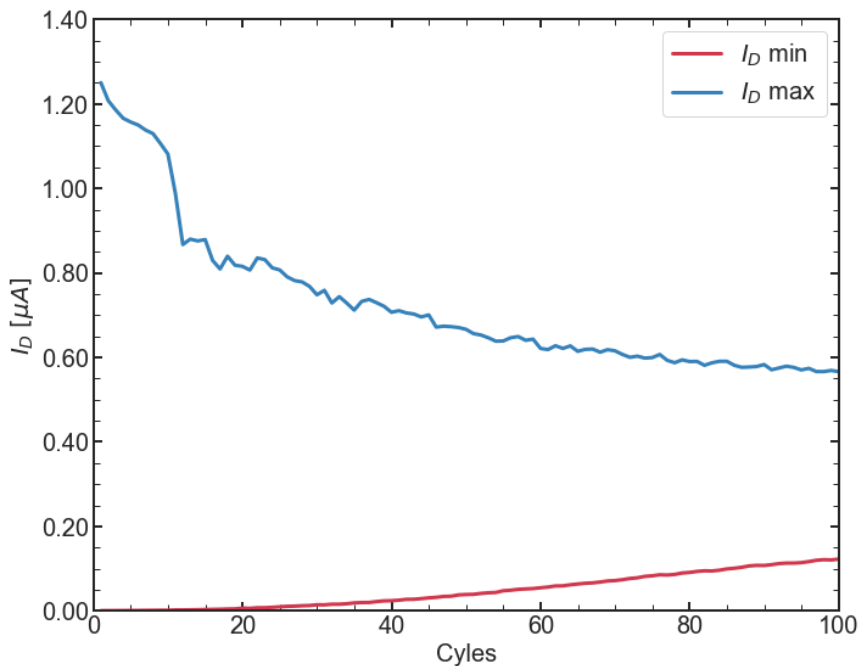
Endurance of Intermediate States

- Sequence 3 shows slight degradation during 600 pulses (20 cycles)
- Increasing asymmetry between LTP and LTD
- Nonlinearity does not deviate strongly during 100 cycles



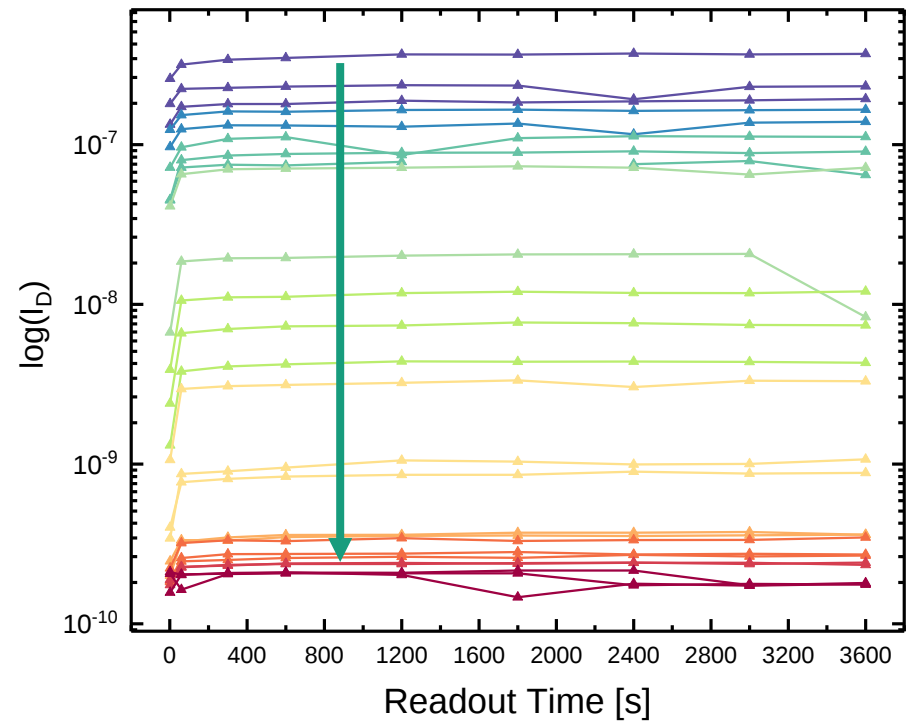
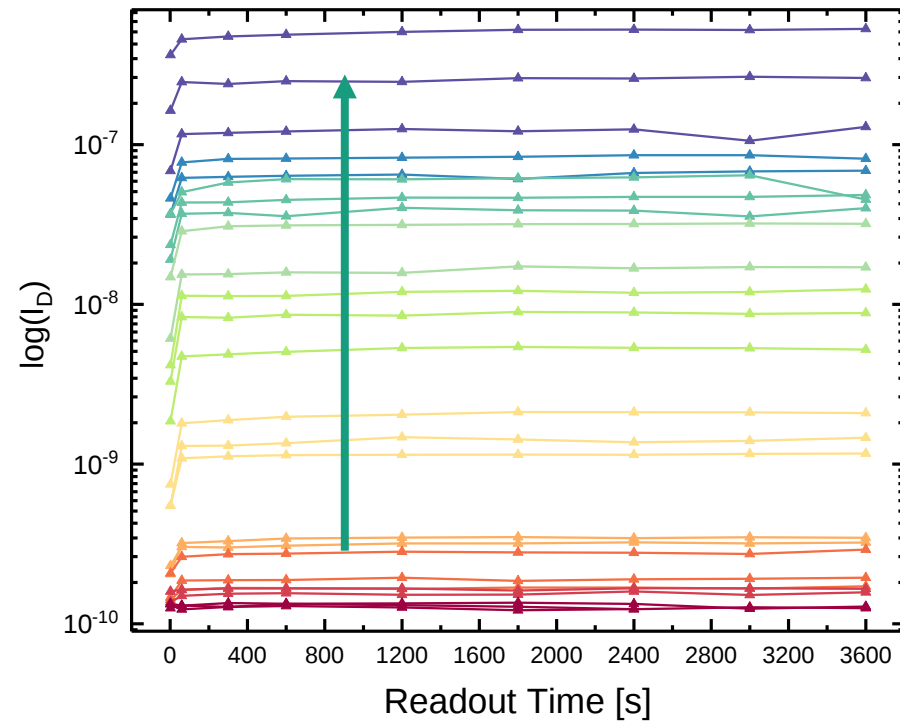
Endurance of Intermediate States

- Sequence 2 shows slight degradation during 4000 pulses (100 cycles)
- Nonlinearity does not deviate strongly during 100 cycles



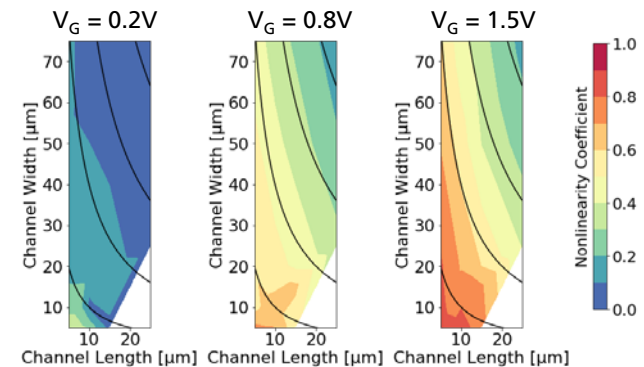
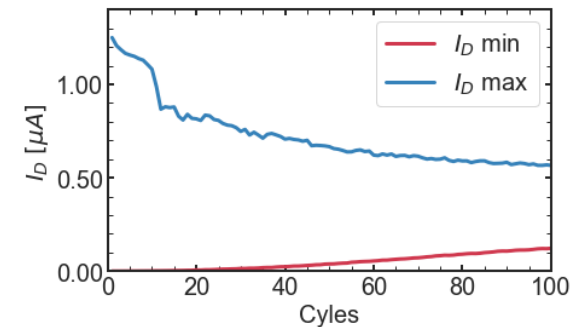
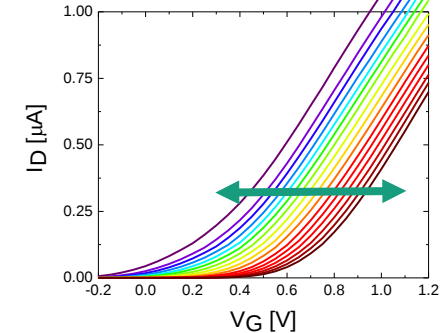
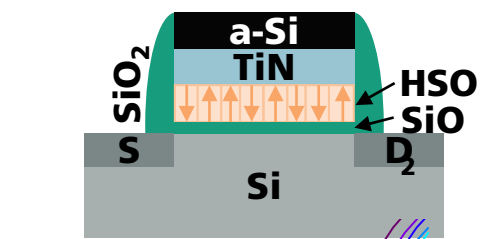
Retention of Intermediate States

- No retention loss for a readout time up to 1 h

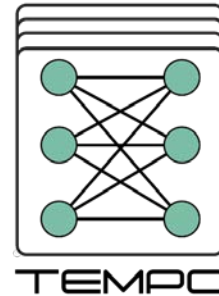


Conclusion & Outlook

- Nonlinearity and dynamic range can be tuned by signal shape and gate voltage
 - Scaling of area without strong increase in nonlinearity possible for sequence 2 and 3
 - Device layout influences nonlinearity
 - Good retention during 1h measurement
 - Slight degradation during 4000 pulses for sequence 2
- FeFETs can be tuned for certain applications

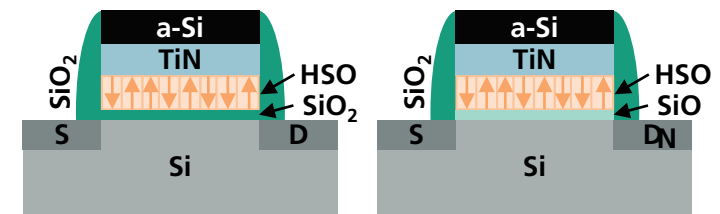
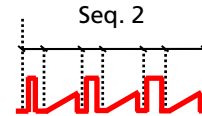


Acknowledgements

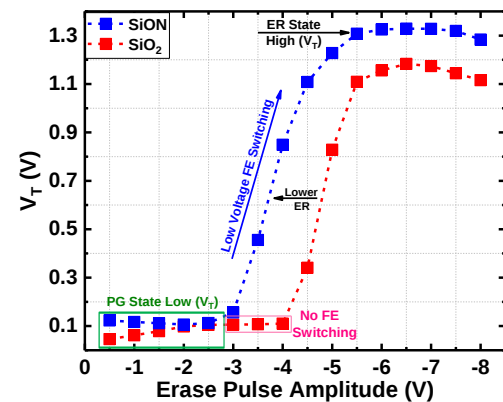


We received funding within the ECSEL Joint Undertaking project TEMPO in collaboration with the European Union's H2020 Framework Program (H2020/2014-2020) and National Authorities, under grant agreement number 783176.

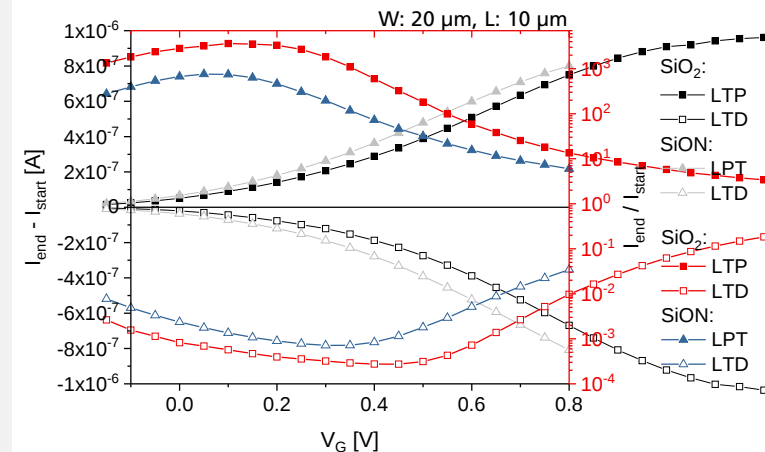
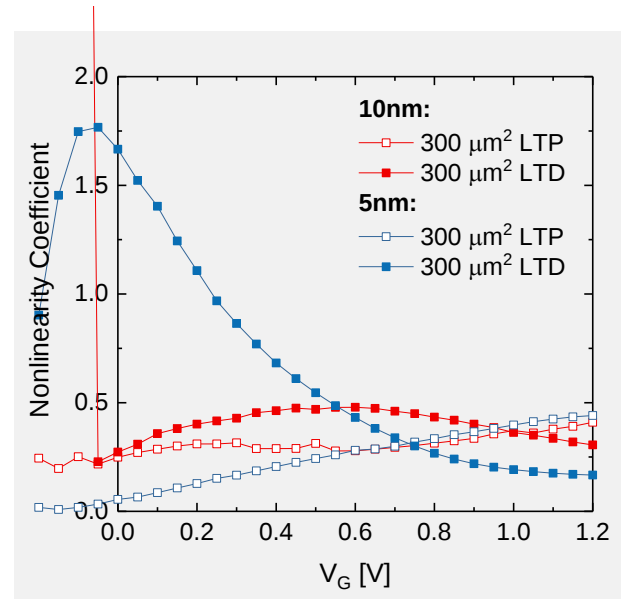
FeFET SiO₂ vs SiON



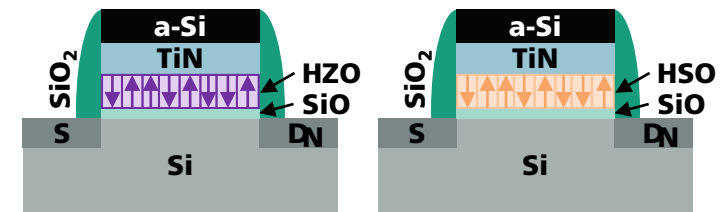
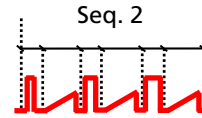
- SiON: Lower voltages necessary to switch fully → Increase in nonlinearity



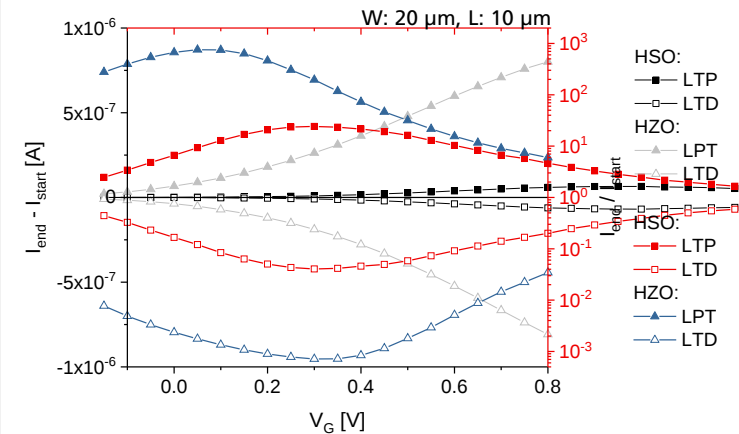
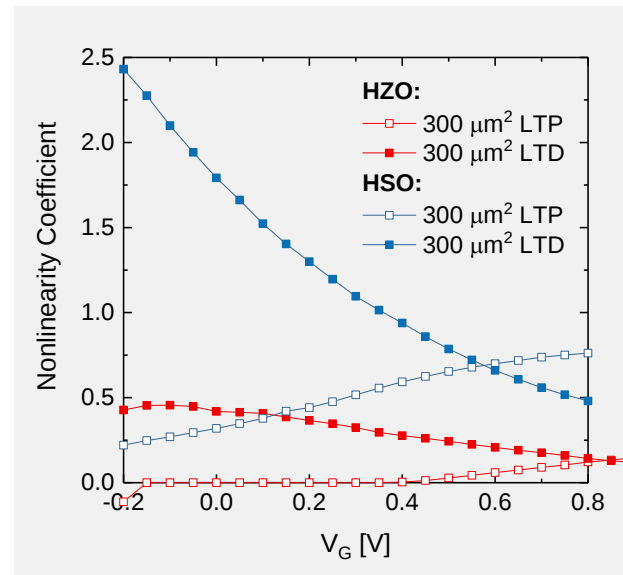
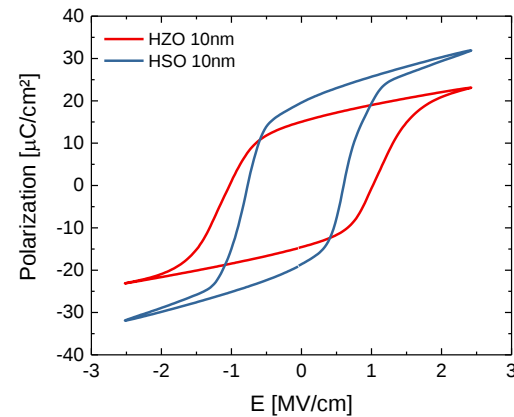
T. Ali et al., TED (2018)



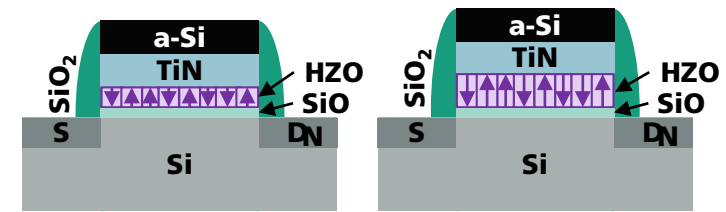
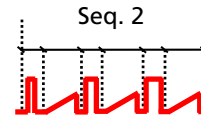
FeFET HSO vs HZO



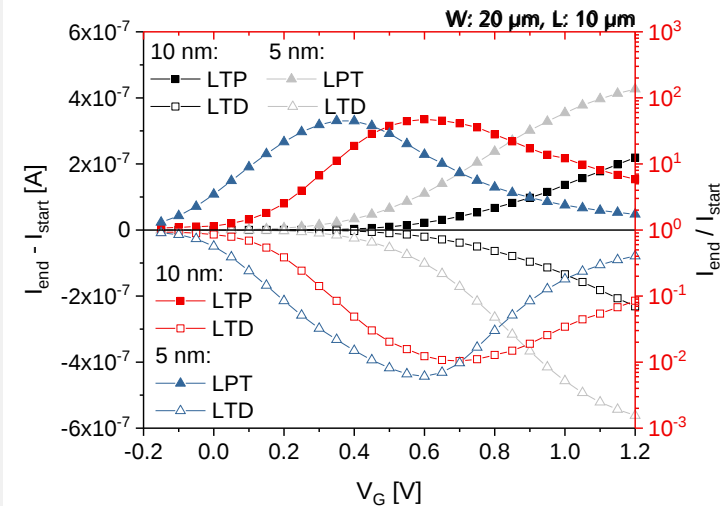
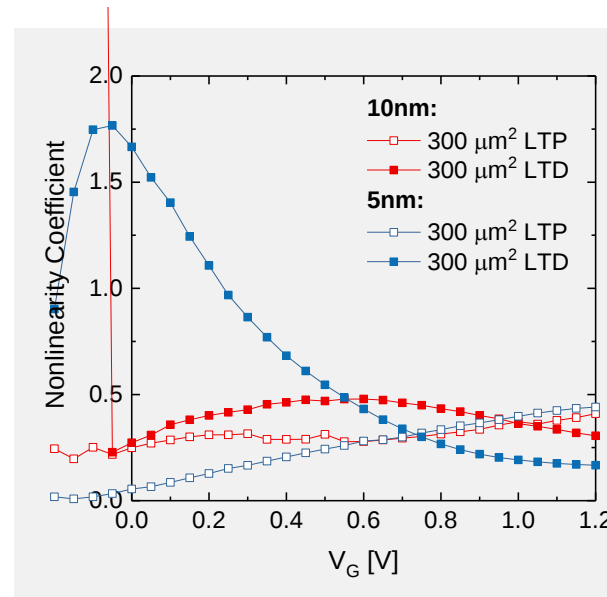
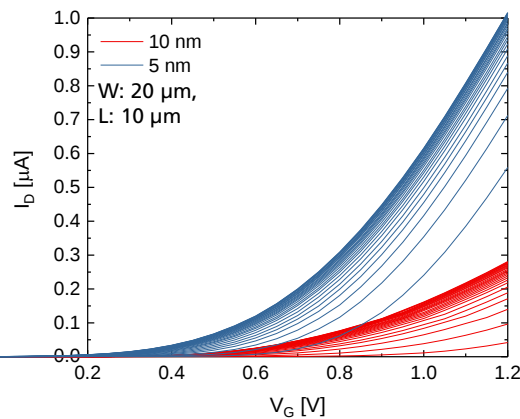
- Lower Variance due to larger MW (FeFET Comparison) not reaching saturation current
- More Subloop Behaviour → Lower nonlinearity coefficient



FeFET thickness influence



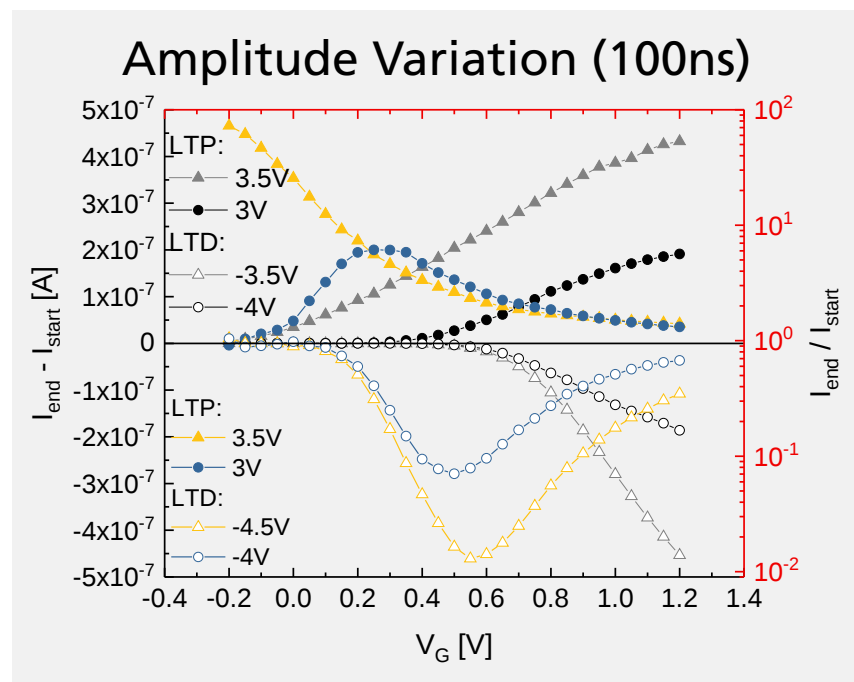
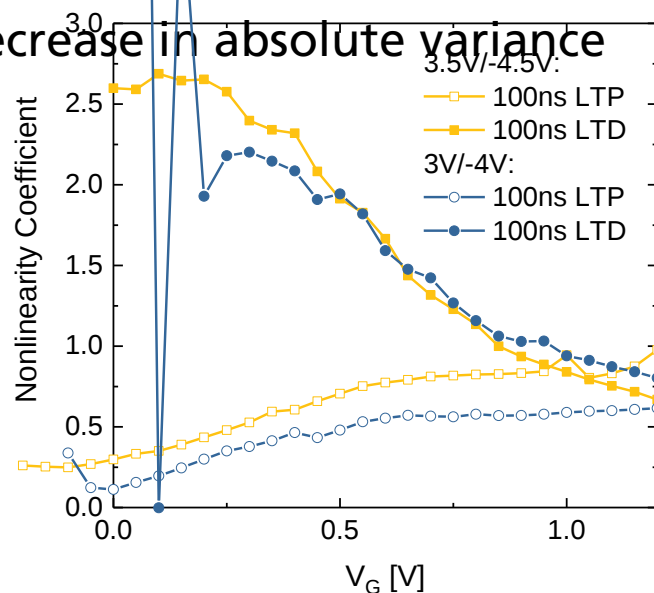
- Thinner film results in an increased electrical field → Compressed / steeper behaviour with V_G



Sequence 1: Pulse Amplitude

Amplitude reduction:

- Decrease of nonlinearity in potentiation
- Reduced assymetry of the variance
- Decrease in absolute variance



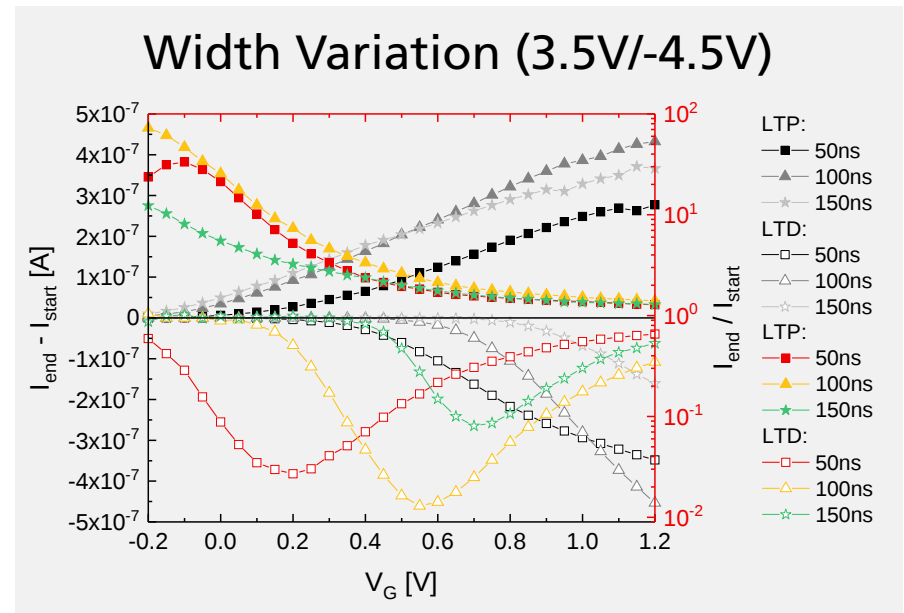
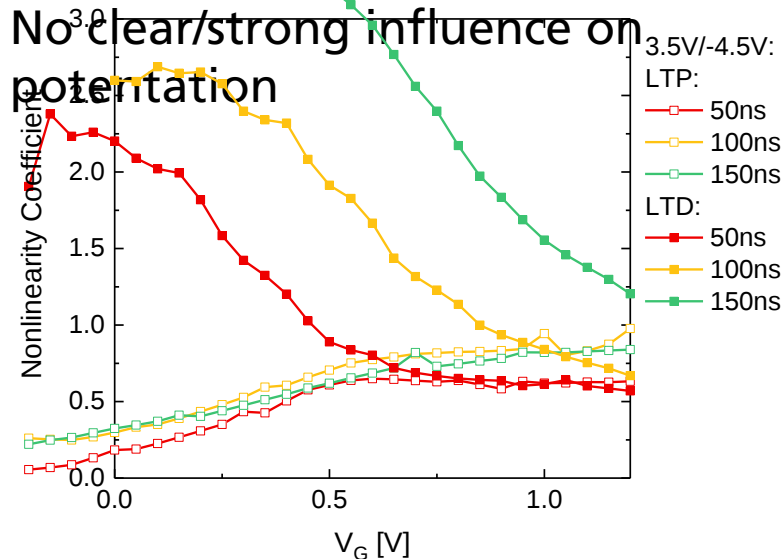
Sequence 1: Pulse Width

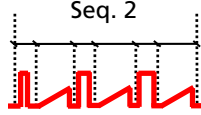
Strong effect on depression

Moving to lower V_G

Converging at ~ 0.5

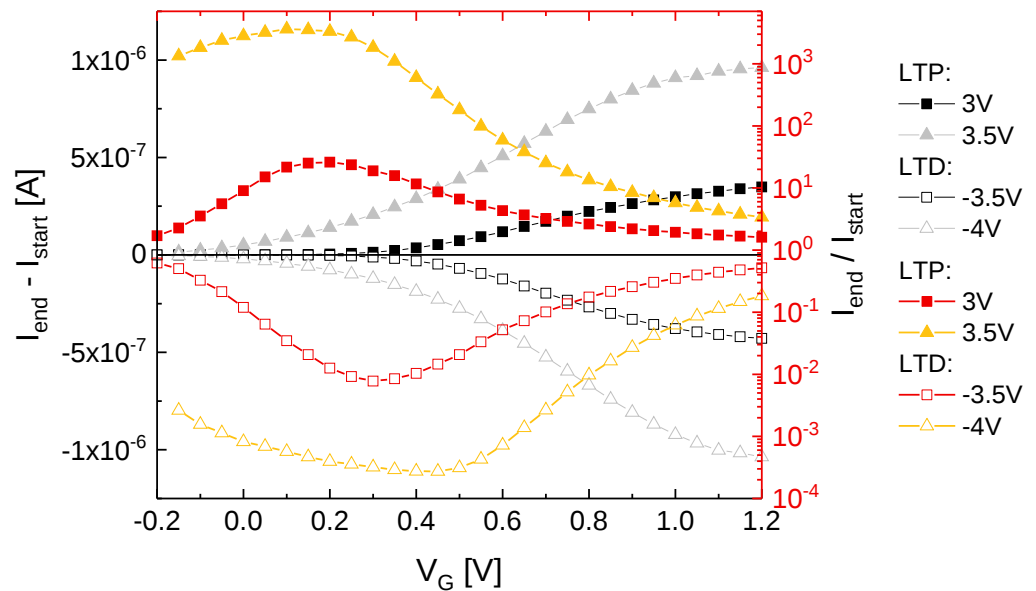
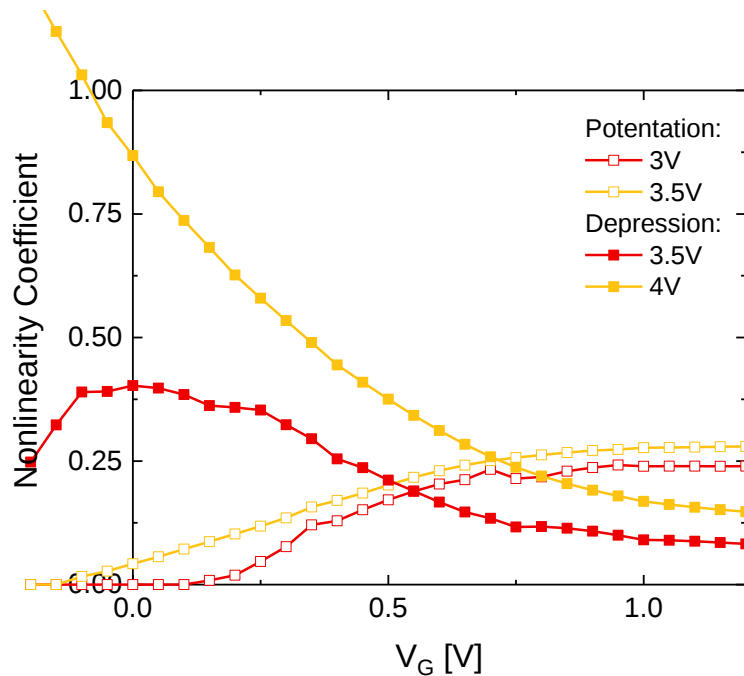
No clear/strong influence on potentiation

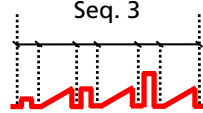




Sequence 2: Pulse Amplitude

■ Trade-off between nonlinearity and variance





Sequence 3: Pulse Width

- Longer pulses increase slope of nonlinearity
- Absolute variance reaches maximum for 100ns
- Variance improvements with higher number of pulses

